

We claim:

1           1. A method of evaluating tolerances of computer assisted designs for  
2 the manufacture of objects comprising:  
3           representing each tolerance zone for each geometric feature of said object by a  
4 model with an algebraic form and a geometric form as a tolerance map stored in a  
5 computer;  
6           computing in said computer interdependencies between said stored maps and  
7 interdependencies between submaps of said stored maps to determine how different  
8 tolerance zones for said geometric feature affect each other and to determine how  
9 different tolerance zones for different geometric features of said object affect each other;  
10 and  
11          selecting tolerance conditions for said object to optimize allocation of tolerances to  
12 each of said geometric features of said object.

1           2. The method of claim 1 where representing each tolerance zone for  
2 each geometric feature of said object comprises a tolerance map representing a plane.  
3           3. The method of claim 1 where representing each tolerance zone for  
2 each geometric feature of said object comprises a tolerance map representing a axis or  
3 edge.

1           4. The method of claim 1 where representing each tolerance zone for  
2    ~~each geometric feature of said object comprises a tolerance map representing a~~  
3    cylindrical surface.

1           5. The method of claim 1 where representing each tolerance zone for  
2    each geometric feature of said object comprises a tolerance map representing a position.

1           6. The method of claim 1 where representing each tolerance zone for  
2    each geometric feature of said object comprises a tolerance map representing composite  
3    tolerances constructed as a Minkowski sum.

1           7. The method of claim 1 where representing each tolerance zone for  
2    each geometric feature of said object comprises a tolerance map in a space of points of  
3    variational possibilities of features of said object.

1           8. The method of claim 1 where representing each tolerance zone for  
2    each geometric feature of said object comprises a tolerance map in a space of points of  
3    variational possibilities of features of said object.

1           9. The method of claim 2 where representing each tolerance zone for  
2    each geometric feature of said object comprises a tolerance map in a space of points of  
3    variational possibilities of features of said object expressed in Barycentric coordinates.

1           10. The method of claim 1 where computing in said computer  
2   interdependencies between said stored maps and interdependencies between submaps  
3   of said stored maps comprises superimposing on a tolerance zone of said geometric  
4   feature a tolerance zone specifying parallelism of variations of said geometric feature.

1           11. The method of claim 1 where computing in said computer  
2   interdependencies between said stored maps and interdependencies between submaps  
3   of said stored maps comprises superimposing on a tolerance zone of said geometric  
4   feature a tolerance zone specifying flatness of said geometric feature.

1           12. The method of claim 1 where computing in said computer  
2   interdependencies between said stored maps and interdependencies between submaps  
3   of said stored maps comprises generating a tolerance zone of an assembled geometric  
4   feature for a assembly of at least two objects, each of which objects has a corresponding  
5   tolerance zone for corresponding geometric features which are being assembled to  
6   comprise said assembled geometric feature.

1           13. The method of claim 4 where representing each tolerance zone for  
2   each geometric feature of said object comprises a tolerance map in a space of points of  
3   said object expressed in Pluecker coordinates.

1           14. The method of claim 3 where representing each tolerance zone for  
2   each geometric feature of said object comprises a tolerance map in a space of points of  
3   said object expressed in terms of line-solids.

1           15. The method of claim 4 where representing each tolerance zone for  
2   each geometric feature of said object comprises a tolerance map in a space of points of  
3   said object for size of cylindrical surfaces is expressed in terms of screw coordinates.

1           16. The method of claim 1 further comprising establishing a global model  
2   by mapping surfaces used as datum or targets in a dimensioning scheme to equivalent  
3   control frames in which datum reference frames are rigid sets and validated using degree  
4   of freedom algebraic operations, and by representing dimensions and tolerances by the  
5   union of corresponding control frames involving the datum and target rigid sets and  
6   corresponding tolerance classes.

1           17. The method of claim 16 wherein mapping surfaces used as datum or  
2   targets in a dimensioning scheme to equivalent control frames comprises forming datum  
3   reference frames as rigid sets for target features and feature patterns.

1           18. The method of claim 17 wherein mapping surfaces used as datum or  
2   targets in a dimensioning scheme to equivalent control frames in which datum reference  
3   frames are formed as rigid sets for a circular pattern of bolt holes.

1           19. The method of claim 16 further comprising identifying redundant or  
2 conflicting restraints by using a degree of freedom algebra on control frames by  
3 determining whether the corresponding datum reference frame is a rigid set and the  
4 maximum degrees of freedom which said datum reference frame controls.

1           20. An apparatus for geometric variations to integrate parametric CAD  
2 with tolerance analysis and optimization of a manufactured object comprising a computer  
3 wherein is stored:  
4           a geometry engine module E1 to generate a B-rep solid model of said object;  
5           a constraint solver E2 to generate a D&T graph of said object;  
6           a geometry engine system M1 communicated to said geometry engine module E1  
7 and constraint solver E2;  
8           a dimensioning module M2 for receiving said B-rep solid model and said D&T  
9 graph as input data;  
10          a tolerancing module M4 communicating with said dimensioning module M2;  
11          a global visualization module M3 communicating with said tolerancing module M4;  
12          a D&T Schema Advisor module M5 communicating with said tolerancing module  
13 M4;  
14          a tolerance allocation module M6 communicating with said tolerancing module M4;  
15          a local model visualization module M7 communicating with said tolerance allocation  
16 module M6 for providing a geometric visualization of tolerancing of said object; and  
17          a statistical tolerance analysis package E3 communicating with said tolerance  
18 allocation module M6 for providing an algebraic visualization of tolerancing of said object.